

A Computationally Grounded Framework for Cognitive Attitudes

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Formal semantics for logics of cognitive attitudes

- Two types of cognitive attitudes
 - ▶ Epistemic: belief, knowledge, acceptance,...
 - ▶ Motivational: desire, goal, preference,...

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Formal semantics for logics of cognitive attitudes

- Two types of cognitive attitudes
 - ▶ Epistemic: belief, knowledge, acceptance,...
 - ▶ Motivational: desire, goal, preference,...
- Standard approach: multi-relational Kripke structures
- Main limitation: **they are not succinct**
 - ▶ Number of possible worlds is huge in real applications
 - ▶ $\binom{20}{5} \times \binom{15}{5} \times \binom{10}{5} \times \binom{5}{5} = 1.1732745024 \times 10^{10}$ possible equitable distributions of 20 different fruits between 4 agents



Our contribution

- Novel approach to cognitive attitudes and their interrelations relying on the notion of **belief base**
- Idea of using belief bases as a semantics for multi-agent epistemic logic has been elaborated in previous work:

Lorini, E. (2020). Rethinking Epistemic Logic with Belief Bases. *Artificial Intelligence*, 282.

Lorini, E. (2018). In Praise of Belief Bases: Doing Epistemic Logic Without Possible Worlds. *AAAI-2018*.

Our contribution

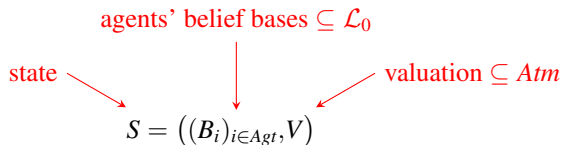
- Novel approach to cognitive attitudes and their interrelations relying on the notion of **belief base**
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- **Advantages:**
 - ▶ Succinct semantics: agents' accessibility relations computed from their belief bases
 - ▶ Well-suited for model checking and epistemic/cognitive planning

Semantics: state



$\mathcal{L}_0 \stackrel{\text{def}}{=} \alpha ::= p \mid \neg \alpha \mid \alpha \wedge \alpha \mid \Delta_i \alpha \quad \Delta_i \alpha : \text{“agent } i \text{ explicitly believes that } \alpha\text{”}$

with p ranging over Atm

$$\begin{array}{ll} S \models p & \text{if } p \in V \\ S \models \neg \alpha & \text{if } S \not\models \alpha \\ S \models \alpha_1 \wedge \alpha_2 & \text{if } S \models \alpha_1 \text{ and } S \models \alpha_2 \\ S \models \Delta_i \alpha & \text{if } \alpha \in B_i \end{array}$$

Semantics: desire bases

Appetitive desire base $D_i^+(S) = \{\alpha \in \mathcal{L}_0 : \alpha \rightarrow \mathbf{good}_i \in B_i\}$

Aversive desire base $D_i^-(S) = \{\alpha \in \mathcal{L}_0 : \alpha \rightarrow \mathbf{bad}_i \in B_i\}$

Non-Humean view: desire-as-belief (DAB) thesis [Lewis, 1988]

Semantics: accessibility relations

Let $S = ((B_i)_{i \in \text{Agt}}, V)$, $S' = ((B'_i)_{i \in \text{Agt}}, V')$ be two states. Then,

Epistemic relation: $S\mathcal{E}_i S'$ if and only if $\forall \alpha \in B_i, S' \models \alpha$

Attraction relation: $S\mathcal{A}_i S'$ if and only if $\exists \alpha \in D_i^+(S)$ s.t. $S' \models \alpha$

Repulsion relation: $S\mathcal{R}_i S'$ if and only if $\exists \alpha \in D_i^-(S)$ s.t. $S' \models \alpha$

Language

$$\mathcal{L} \stackrel{\text{def}}{=} \varphi ::= \alpha \mid \neg\varphi \mid \varphi \wedge \varphi \mid \Box_i\varphi \mid \odot_i\varphi \mid \ominus_i\varphi \mid [\odot]_i\varphi \mid [\ominus]_i\varphi$$

with α ranging over \mathcal{L}_0 and i ranging over Agt

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with α ranging over \mathcal{L}_0 and i ranging over Agt

$\Box_i\varphi$: “agent i implicitly believes that φ ”

$\odot_i\varphi$: “agent i is completely attracted to the fact that φ ”

$\ominus_i\varphi$: “agent i is completely repelled by the fact that φ ”

$[\odot]_i\varphi$: “agent i is realistically attracted to the fact that φ ”

$[\ominus]_i\varphi$: “agent i is realistically repelled by the fact that φ ”

Interpretation of formulas

Wrt a state S and a set of states (*context*) U :

$$(S, U) \models \alpha \quad \text{if} \quad S \models \alpha$$

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Theorem

The operators \odot_i , \ominus_i , $[\odot]_i$ and $[\ominus]_i$ are not expressible with the other modalities or each other.

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The operators \odot_i , \ominus_i , $[\odot]_i$ and $[\ominus]_i$ are not expressible with the other modalities or each other.

\Rightarrow A sound and complete axiomatization is given in the paper

Cognitive positions and preferences

<u>def</u>	$\odot_i \varphi$	$\neg \odot_i \varphi$
$\odot_i \varphi$	$A_i \varphi$ (ambivalent)	$M_i^\downarrow \varphi$ (demotivated)
$\neg \odot_i \varphi$	$M_i^\uparrow \varphi$ (motivated)	$I_i \varphi$ (indifferent)

Table: Cognitive attitudes

<u>def</u>	$[\odot]_i \varphi$	$\neg [\odot]_i \varphi$
$[\odot]_i \varphi$	$RA_i \varphi$ (realistically ambivalent)	$RM_i^\downarrow \varphi$ (realistically demotivated)
$\neg [\odot]_i \varphi$	$RM_i^\uparrow \varphi$ (realistically motivated)	$RI_i \varphi$ (realistically indifferent)

Table: Realistic cognitive attitudes

Cognitive positions and preferences

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$$\psi \prec_i \varphi \stackrel{\text{def}}{=} (M_i^\uparrow \varphi \wedge \neg M_i^\uparrow \psi) \vee (M_i^\downarrow \psi \wedge \neg M_i^\downarrow \varphi)$$

$$\psi \prec_i^{\text{real}} \varphi \stackrel{\text{def}}{=} (RM_i^\uparrow \varphi \wedge \neg RM_i^\uparrow \psi) \vee (RM_i^\downarrow \psi \wedge \neg RM_i^\downarrow \varphi)$$

For $\blacktriangleleft \in \{\prec_i, \prec_i^{\text{real}}\}$:

$$\begin{aligned} &\models \neg(\varphi \blacktriangleleft \varphi) \\ &\models (\psi \blacktriangleleft \varphi) \rightarrow \neg(\varphi \blacktriangleleft \psi) \\ &\models ((\varphi_1 \blacktriangleleft \varphi_2) \wedge (\varphi_2 \blacktriangleleft \varphi_3)) \rightarrow (\varphi_1 \blacktriangleleft \varphi_3) \end{aligned}$$

\mathcal{L}_{dyn} : extension with dynamic operators $[\pi]$

$$\mathcal{L}_{\text{prog}} \stackrel{\text{def}}{=} \pi ::= \overset{\text{belief expansion}}{+_i \alpha} \mid \overset{\text{belief forgetting}}{-_i \alpha} \mid \pi; \pi \mid \pi \cup \pi \mid ?\varphi$$

$[\pi]\varphi$: “ φ holds after program π has been executed”

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$[\pi]\varphi$: “ φ holds after program π has been executed”

$$(S, U) \models [\pi]\varphi \quad \text{if} \quad \forall S' \in U, \text{ if } SP_{\pi}^U S' \text{ then } (S', U) \models \varphi$$

with:

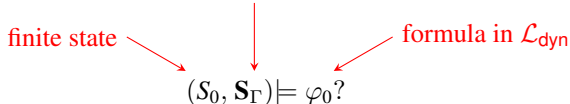
$$\begin{aligned} SP_{+_i \alpha}^U S' & \text{ iff } V = V', B_i^{+_i \alpha} = B_i \cup \{\alpha\} \text{ and } \forall j \neq i, B_j^{+_i \alpha} = B_j \\ SP_{-_i \alpha}^U S' & \text{ iff } V = V', B_i^{-_i \alpha} = B_i \setminus \{\alpha\} \text{ and } \forall j \neq i, B_j^{-_i \alpha} = B_j \\ SP_{\pi_1; \pi_2}^U S' & \text{ iff } \exists S'' \in U \text{ such that } SP_{\pi_1}^U S'' \text{ and } S'' \mathcal{P}_{\pi_2}^U S' \\ SP_{\pi_1 \cup \pi_2}^U S' & \text{ iff } SP_{\pi_1}^U S' \text{ or } SP_{\pi_2}^U S' \\ SP_{?\varphi}^U S' & \text{ iff } S' = S \text{ and } (S, U) \models \varphi \end{aligned}$$

Model checking

context induced by agent vocabulary profile $\Gamma = (\Gamma_i)_{i \in \text{Agt}}$

finite state

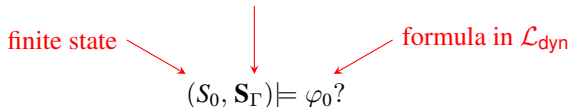
formula in \mathcal{L}_{dyn}


$$(S_0, \mathbf{S}_\Gamma) \models \varphi_0?$$

$$\mathbf{S}_\Gamma = \left\{ S = ((B_i)_{i \in \text{Agt}}, V) \in \mathbf{S} : \forall i \in \text{Agt}, B_i \subseteq \Gamma_i \right\} \text{ with } \Gamma_i \subseteq \mathcal{L}_0 \text{ finite}$$

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Theorem

The model checking problem for \mathcal{L}_{dyn} is PSPACE-complete.

Poly-size reduction into TQBF given in the paper

Example: Bob and the messy room



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$$S_0 = (B_{Bob}, V_0)$$

$$B_{Bob} = \{td_{Bob} \rightarrow ti_{Bob},$$

$$ti_{Bob} \rightarrow bad_{Bob},$$

$$cr_{Bob} \rightarrow good_{Bob},$$

$$\neg tv_{Bob} \rightarrow bad_{Bob}\}$$

$$V_0 = \emptyset$$

$$(S_0, S_\Gamma) \models (td_{Bob} \prec_{Bob}^{real} \neg td_{Bob})$$

$$\text{with } \Gamma = (B_{Bob})$$

Example: Bob and the messy room



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$$A_1 \stackrel{\text{def}}{=} +_{Bob} (\neg td_{Bob} \rightarrow \neg tv_{Bob})$$

$$A_2 \stackrel{\text{def}}{=} +_{Bob} (td_{Bob} \rightarrow cr_{Bob})$$

$$A_3 \stackrel{\text{def}}{=} -_{Bob} (td_{Bob} \rightarrow ti_{Bob})$$

$$\pi_{talk} \stackrel{\text{def}}{=} \bigcup_{\substack{A, A' \in \{A_1, A_2, A_3\}: \\ A \neq A'}} A; A'$$

$$(S_0, \mathbf{S}_\Gamma) \models [\pi_{talk}] (\neg td_{Bob} \prec_{Bob}^{real} td_{Bob})$$

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$$(S_0, \mathbf{S}_\Gamma) \models [\pi_{\text{talk}}](\neg td_{Bob} \prec_{Bob}^{\text{real}} td_{Bob})$$

Generalized to k children in the paper!

Experimental analysis

$ Agt $	1	10	20	40	60
$ Atm $	6	60	120	240	360
$ \Gamma_i $	4	4	4	4	4
$ \mathbf{S}_\Gamma $	2^{18}	2^{180}	2^{360}	2^{720}	2^{1080}
exec. time (sec.)	0.07	0.19	0.57	2.38	5.67

Table: Model checker performance on the example.